

Model 89000B

PATHFINDER MAZE SYSTEM ASSEMBLY INSTRUCTIONS

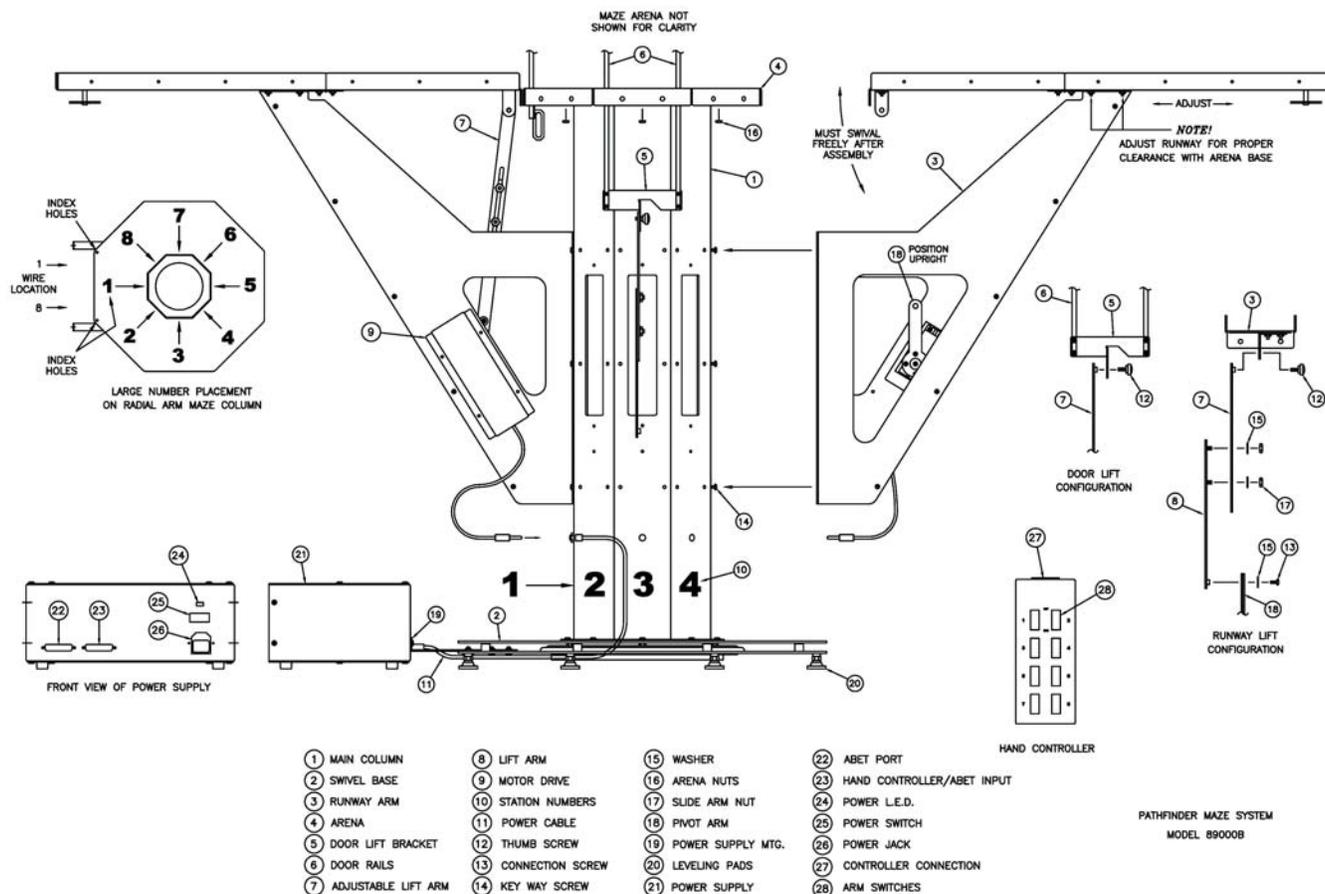
Electronic Radial Arm Maze



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Table of Contents:

(A) Installation of the Arena to the Column	3
(B) Installation of Runway Arms to the Column	3
(C) Connection of Lift Arms to the Runways & Doors	4
(D) Attaching the Power Control Box	5
(E) Attaching the Switchbox	5
(F) Installation of the Runway/Bridge Walls	6
(G) Connection to ABET	7
(H) Connection to Photocell Runway Monitor	8
(I) Example ABET Schedule	9
Appendix 1 - Main Assembly Diagram	10
Appendix 2 - Detail of Bridge Diagram	11
Appendix 3 - Runway Wall Assembly Diagram	12
Appendix 4 - Area Configurations Diagram	13
Ordering Information	14



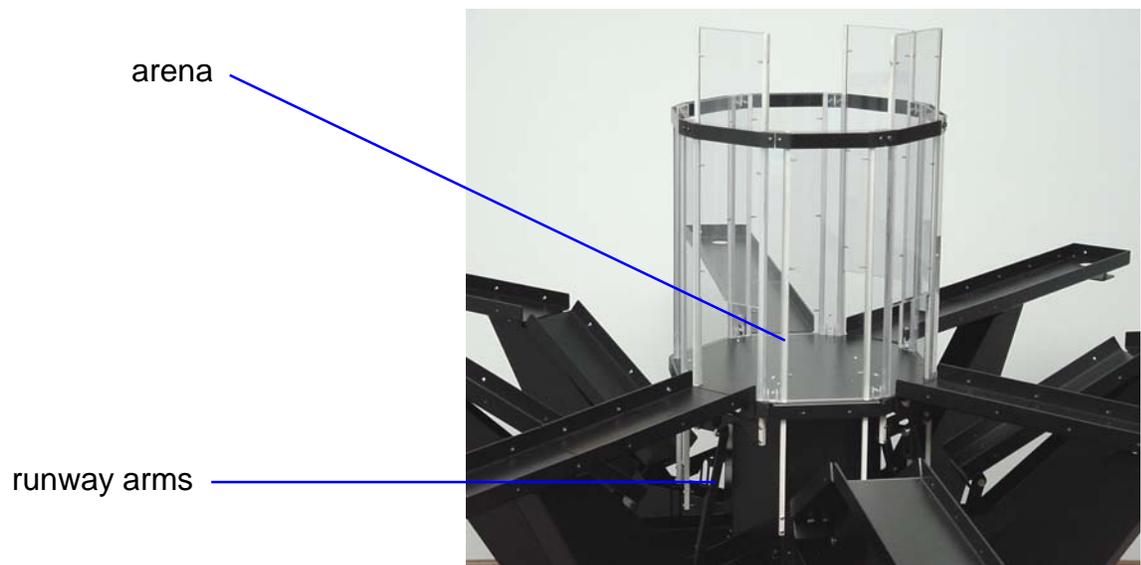
Assembly Instructions:

(A) Installation of the Arena to the Column

***See diagram on page 10**

Required tools: 5/16" nut driver

1. Place arena on top of the column, assuring that all (8) threaded studs are seated into the mating slots. Install the (8) keps nuts provided and tighten securely.
2. Check for smooth sliding of the arena doors after installing.



(B) Installation of Runway Arms to the Column

***See diagram on page 10**

Required tools: medium size Phillips head screwdriver

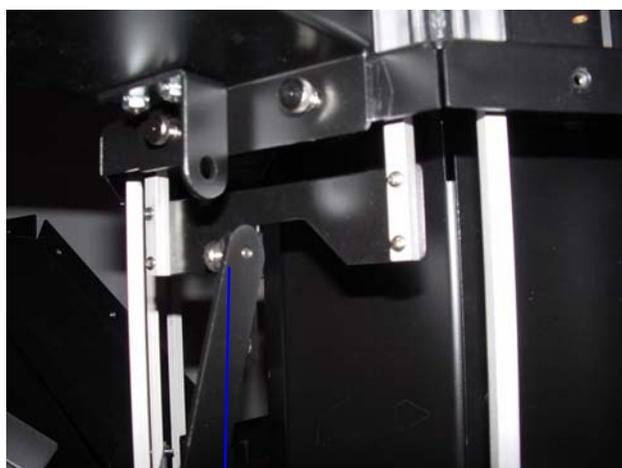
1. Mount all eight runway arms to the column. Each arm has keyway slots located on the back of the arm tabs. Once mounted, tighten all (6) keyway screws securely. (Runway arms can be installed in any order.)
2. Each arm has a 3.5mm plug that must be connected to the column. Insert each of the plugs into its proper connector.

(C) Connection of Lift Arms to the Runways & Doors

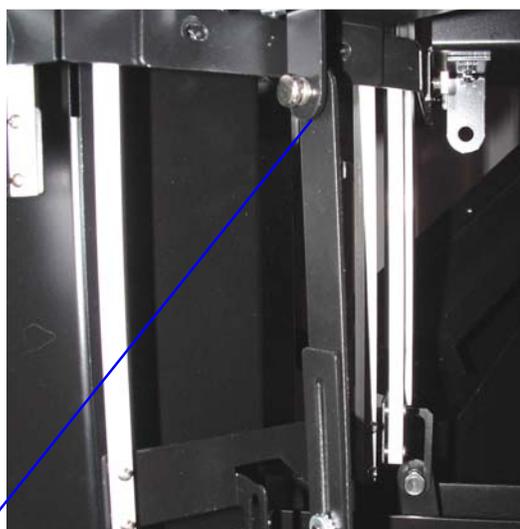
***See diagram on page 10**

Required tools: none

1. At this point you have the option of attaching the lift arms to the under side of the swivel portion of the runways or to the slotted door lift bracket connected to the arena. The provided plastic thumb screws are used for either application. The length of the runways and the doors are adjusted using the slotted liftarm. When switching from runways to door or vise-versa, pay careful attention to the height of the raised runway and the depth of the lowered door. The raised runway should be level with the arena. The lowered door should close gently, not with a loud noise. If it closes with a loud noise, the lift arm should be lengthened.
2. Assure these connections operate smoothly and that there is no binding of the mechanism.
3. Place the eight feeder cups into the open holes located at the end of the runway.
4. At this point rotate the column on the base swivel to assure it moves freely without binding. When the column is positioned with the numeral one facing the cable mounting panel, this is considered the mid point or center of rotation. From this point the column can be rotated 170 degrees to the left or 170 degrees to the right of this center point. The column will not rotate past 170 degrees, as there is a built in rotation stop to prevent the cables from bending.



door connection



runway connection

(D) Power Control Box

***See diagram on page 10**

Required tools: none

1. First, mount the power control box using the two knurl screws at the base of the column.
2. Next, connect the cables to the back of the control box where it is labeled 1 through 8.
3. Connect the IEC cable to the power box, and plug the other side to the 120v outlet.



back of power control box



front of power control box

(E) Switch box

Required tools: None

1. Use the DB-25 cable and attach one side to the switch.
2. Attach the second side of the DB-25 cable to the power box.
3. If you are using a tripod, use the screw mount on the bottom of the switch box.



(F) Installation of the Runway/Bridge Walls

(Closed Configuration ONLY)

*See diagram on page 11

Required tools: 1/16" hex wrench (included)
5/16" nut driver

1. All polycarbonate walls (**F1**, **F3**, and **F7**) are shipped with a special covering that helped protect the walls against scratching. The covering must be removed from all walls. This is easily done by peeling back the corner of the covering and continuing to pull until the covering is off.
2. Begin by installing 2 bridge walls (**F1**) on either side of the bridge. The walls are mounted on the outer side of the bridge wall, with the hex screws inserted through the mounting holes from the inside of the bridge wall (**F5**), through the mounting hole (**F2**), and secured with a kee nut on the outside of the wall. Be sure that the notch (**F4**) is in the correct location, at the intersection of the bridge and runway. At this point, finger tighten the kee nuts. **DO NOT TIGHTEN WITH THE NUT DRIVER!**
3. Continue by installing 2 arm walls (**F3**) on either side of the runway using the same procedure outlined in step #2 above.
4. Install the end wall (**F7**) on the end of the runway using the same basic procedure outlined in step #2 above.
5. Install the corner connectors (**F8**) and the straight connectors (**F9**) in the notched areas of the wall as illustrated in the assembly diagram.
6. Tighten all kee nuts (**F6**) with the nut driver.
7. Repeat steps #2 - #6 for all remaining arms.

(G) Model 89000B Connections for ABET

Required tools: None

Description:

Using the ABET Starter Interface (Model 81401), or an expander interface (Model 81402), connections for Model 89000B can be made to ABET using the following guidelines.

1. Connect the ABET Starter interface to the Model 89000B Power box, using the DB-25 M-F cable. Connect the male end of the cable to the Model 89000B hand controller/ABET input, and the female end of the cable to the starter or expander interface.
2. Connect the Model 89000B Power box to the Model 81408 I/O block, using a second DB-25 cable. Connect the female end of the cable to the Model 89000B ABET port, and the male end of the cable to the Model 81408 I/O Block.
3. Connect the Model 81408 I/O block to the starter or expander interface using a third DB-25 cable. Connect the female end of the cable to the Model 81408 I/O block, and the male end of the cable to the starter or expander interface.

(H) Model 89000B Connections for Photocell Runway Monitor

Required tools: Flathead Screwdriver (included)

Description:

When using the photocell monitors for the runways of the Model 89000B, all photocell connections are made through the Model 81408/09 I/O block. For the Model 89000B you can have a maximum of 16 photocells connected at one time.

1. Locate the first runway, labeled 1. Use the IR mounting kit to mount the photocells on the outside of the Plexiglas walls. Place the photocells on the IR mounts at the desired positions. Usually located at the beginning and/or end of the runway.
2. Connect the first photocell to the Model 81408 I/O block.
 - Red** - +28 VDC
 - Black** - GND
 - Blue** - Normally Open connection (Active Low “gnd”)
 - Clear** - Normally Closed connection (Active High “5v”)
3. Connect the Blue wire of the Model 81413 to input #1 of the Model 81408/09 for the first photocell.
4. Repeat for all remaining photocells, increasing inputs for photocells.
5. Please keep the photocells wiring to the outside of the column.
6. When you apply power to the ABET system with the photocells attached, a red led will light up on the light source. If the receiver detects the light from the source, the red led on the receiver will light up. When the red led on the receiver is off, the light source is not detected. Adjust the photocells to make sure light is detected properly when aligned with the light source. Make sure the red led turns off properly when the light source beam is broken.
7. All photocells from the Model 81413 are configured as inputs on the ABET system. When the light source is detected, its' ABET input will read OFF. When the beam is broken, its' input changes to ON.

Note: *It is important to keep the photocells clean and aligned for proper operation.*

(I) Example ABET Schedule

This schedule allows the animal to explore four arms. It keeps track of the arms explored and then re-explored. Once each of the four arms are explored the schedule ends.

The default arms are #1, #3, #5, and #7 - essentially a plus configuration. To determine exploration, "states" are used to keep track of where the animal has been. Each arm has an associated "state", using the "ArmFlag" counter, and are defined as:

State "0" - Runway not explored

State "1" - Reached end of runway (Cup Sensor)

State "2" - Exiting runway (Entry Sensor)

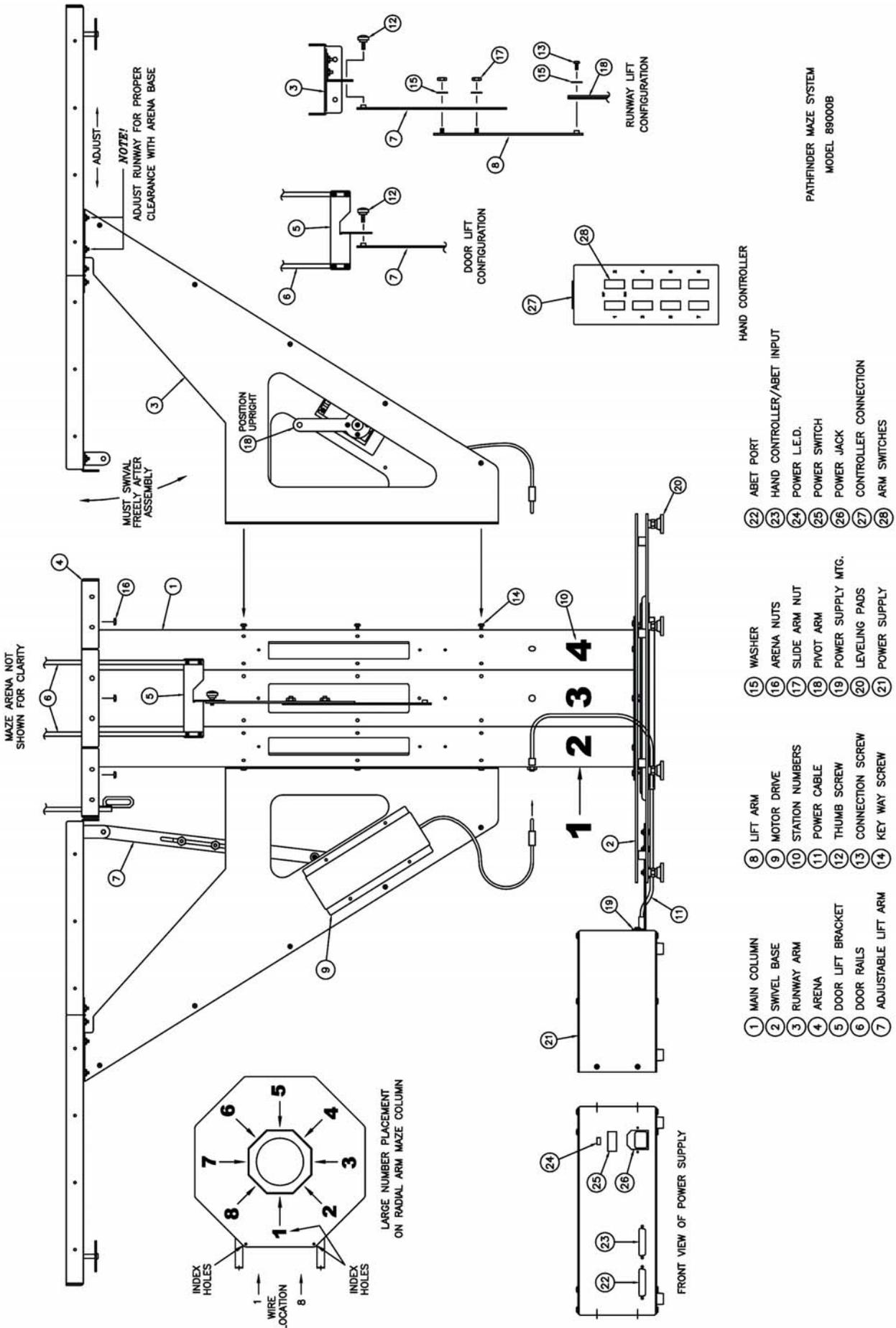
State "3" - Another runway is entered (Entry Sensor on other runways)

To map where the animal has been the counter for each arm is incremented as these "states" are reached. State "3" is unique in that the animal must enter another arm to know it has fully exited the arm explored. The "ArmFlag" is further incremented from 3 onward to indicate the associated runway is re-explored. So, if the "ArmFlag" for runway 1 is incremented to 6 then the runway was re-explored at least two times. Once the "ArmFlag" reaches "3" each Entry Sensor or Cup Sensor detection causes the "ArmFlag" to increment. The resulting data file can be analyzed to determine the amount of re-exploration of an arm, essentially the number of times the Entry Sensor and the Cup Sensor were activated.

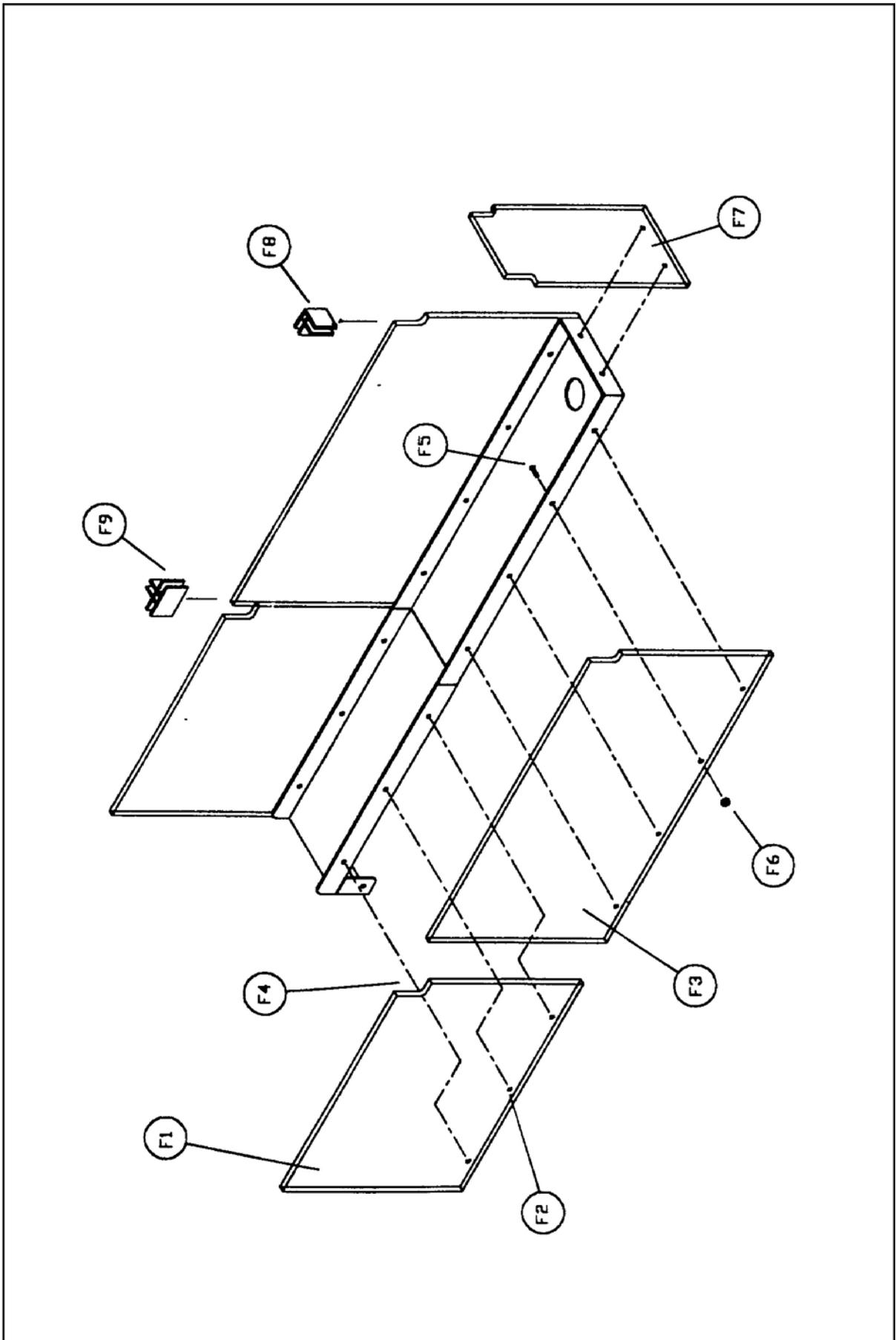
Notes:

1. Automatic Door – Turn ON = Door opened or Bridge raised
2. Automatic Door – Turn OFF = Door closed or Bridge lowered
3. Entry Sensors for arms 1 to 8 are physically wired to inputs 1, 3, 5, 7, 9, 11, 13, 15 respectively.
4. Cup Sensors for arms 1 to 8 are physically wired to inputs 2, 4, 6, 8, 10, 12, 14, 16 respectively.
5. All photocell sensors are wired with the Red wire to 28VDC, Black wire to Common, the Blue wire to the respective input.

Electronic PathFinder Maze System

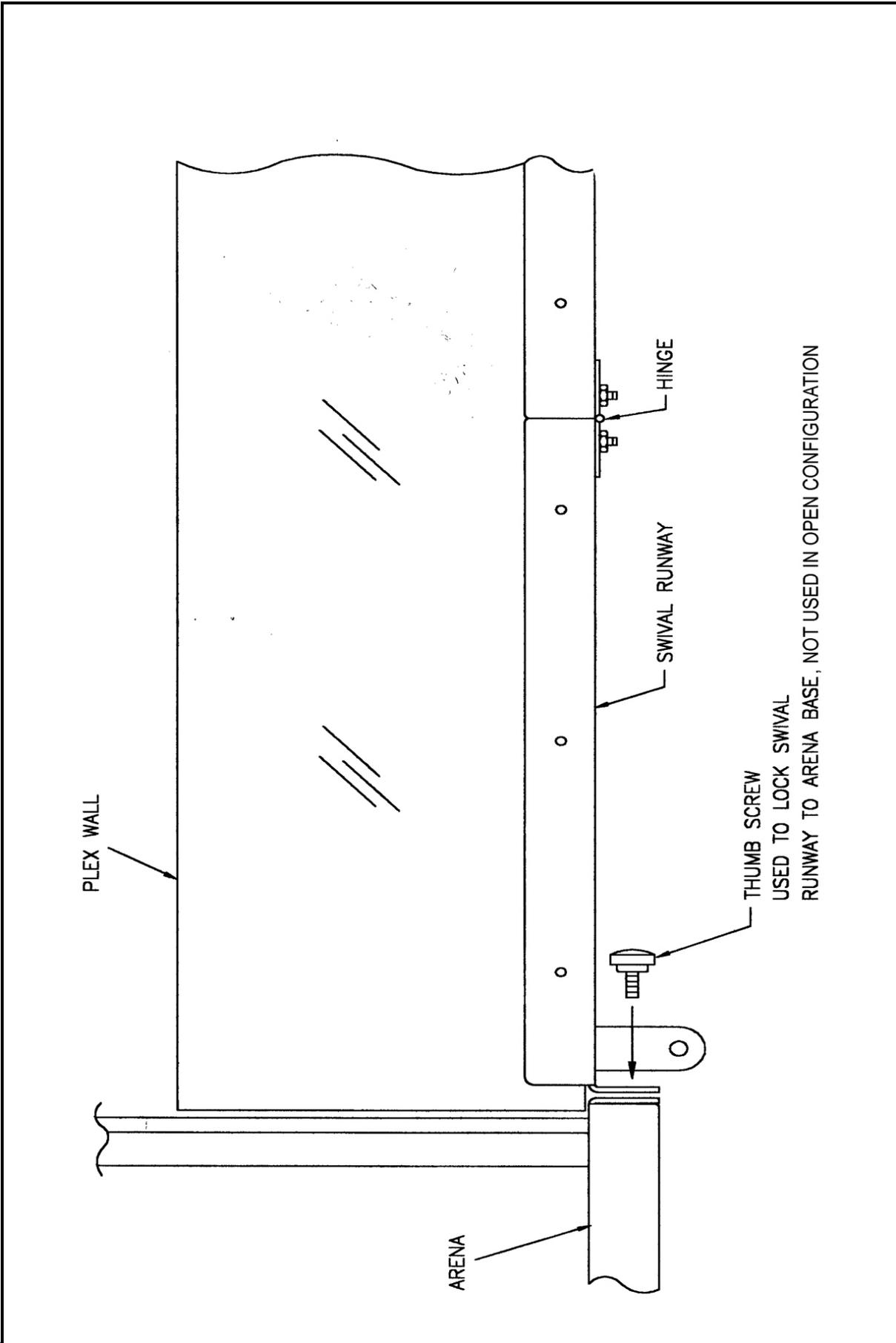


Main Assembly Diagram



Detail of Bridge Diagram

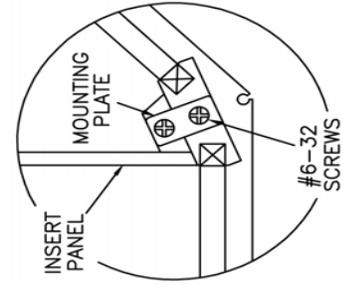
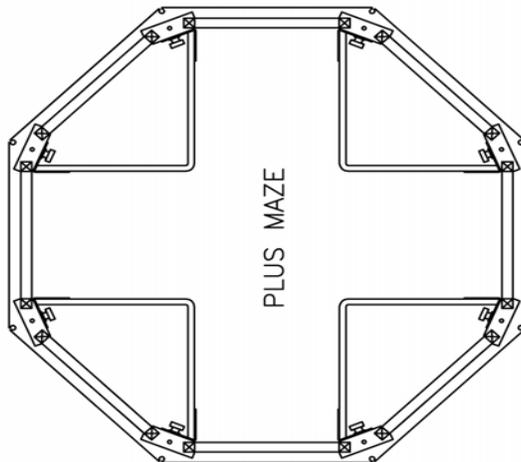
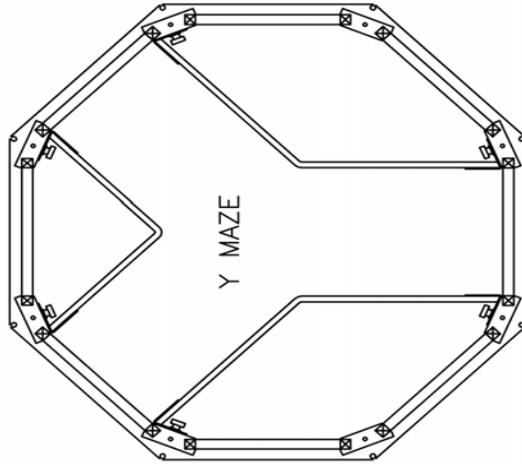
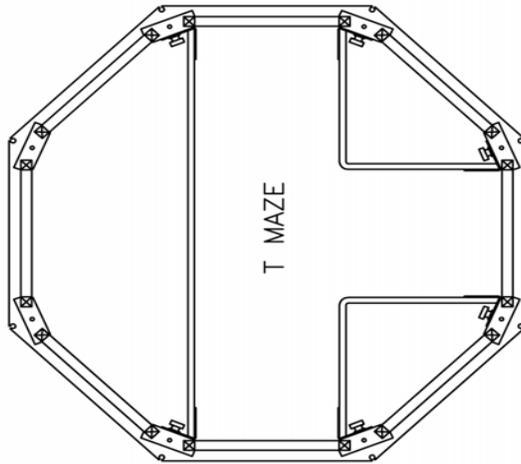
Electronic PathFinder Maze System



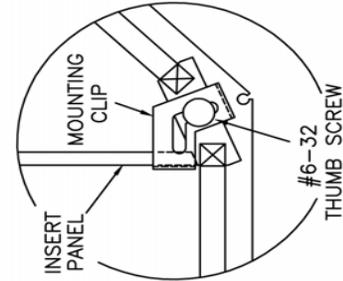
Runway Wall Assembly Diagram

MAZE INSERT KIT CONFIGURATION

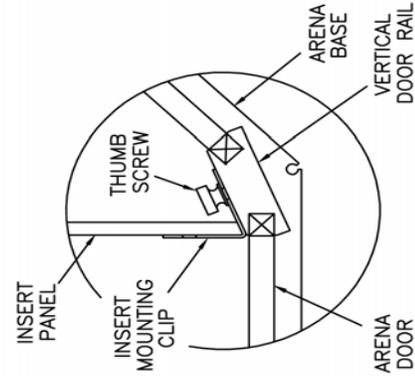
MODELS 89000A & 89000B



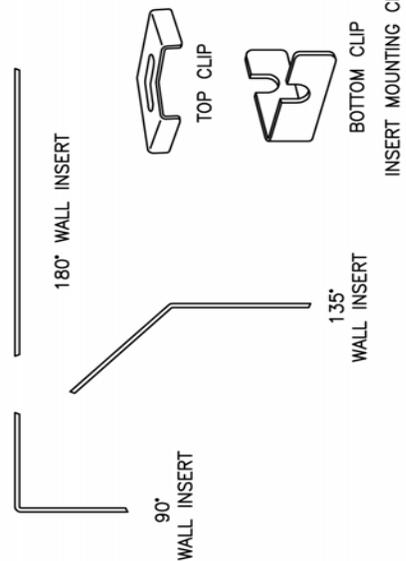
TOP MOUNTING
FOR PRIOR MODELS



TOP MOUNT
TYPICAL INSTALLATION FOR
TOP AND BOTTOM MOUNTS



BOTTOM MOUNT



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- 6) Telephone number

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explaining the malfunction. Please also state the name of the Lafayette Instrument representative authorizing the return. An estimate of repair will be given prior to completion ONLY if requested in your enclosed cover letter. We must have a hard copy of your purchase order by mail or fax, or repair work cannot commence.

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